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# Quantum state tomography including measurement duration, imperfections and decoherence

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## Filtering versus tomography

### Filtering and Stochastic Master Equation (SME)

- Discrete-time case

- Continuous-time (diffusive) case

### State tomography with decoherence and imperfections

- Computation of the likelihood function via the adjoint state

- Qubit tomography based on fluorescence experimental data

## Concluding remarks

- ▶ Tomography of  $\rho$  via  $N$  independent measurements  $\mathbf{Y}$  associated to POVM: probability  $\text{Tr}(\rho\pi_j)$  of each measurement outcome  $j$  given by  $\pi_j$ ; for  $\mathbf{N}_j$  the number of  $j$  outcomes,  $\mathbf{Y} \equiv (\mathbf{N}_j)$  with  $\sum_j \mathbf{N}_j = N$ , the number of measurements.
- ▶ **Several estimation methods:**
  - MaxEnt:**  $\rho_{ME}$  maximizes  $-\text{Tr}(\rho \log(\rho))$  under the constraints  $|\text{Tr}(\rho\pi_j) - \mathbf{N}_j/N| \leq \epsilon$  (Bužek et al, Ann. Phys. 1996).
  - Compress Sensing:**  $\rho_{CS}$  minimizes  $\text{Tr}(\rho)$  under the constraints  $|\text{Tr}(\rho\pi_j) - \mathbf{N}_j/N| \leq \epsilon$  (Gross et al PRL2010)
  - MaxLike:**  $\rho_{ML}$  maximizes the likelihood function,  $\rho \mapsto \mathbb{P}(\mathbf{Y} | \rho) = \prod_j (\text{Tr}(\rho\pi_j))^{\mathbf{N}_j}$  (see, e.g., Lvovsky/Raymer RMP 2009)
  - Bayesian Mean:**  $\rho_{BM} \propto \int \rho \mathbb{P}(\mathbf{Y} | \rho) \mathbb{P}_0(\rho) d\rho$  where  $\mathbb{P}_0$  is some prior distribution  $\mathbb{P}_0(\rho) d\rho$  (see, e.g., Blume-Kohout NJP2010).
  - Low rank, high dimensional systems:** see, e.g, key contributions of **Robert Kosut** and also of **Madalin Guta**.

**Filtering:** estimation of the quantum state  $\rho_t$  at time  $t > 0$  from the measurement trajectory  $[0, t[\ni \tau \mapsto \mathbf{y}_\tau$  and the initial state  $\rho_0$ ; see **Belavkin** similar contributions (links with Monte-Carlo quantum-trajectories).

**State tomography:** estimation of the initial state  $\rho = \rho_0$  from a collection of  $N$  measurement trajectories:  $\mathbf{Y} = \left( \mathbf{y}_t^{(n)} \right)$  with  $n \in \{1, \dots, N\}$  and  $t \in [0, T]$ .

**Process tomography:** estimation of a parameter  $p$  from a known initial state  $\rho_0$  and a collection of  $N$  measurement trajectories  $\mathbf{Y}$ .

**Focus on quantum state tomography:** decoherence, exp. imperfections during the measurement duration  $T$  can be included via the adjoint state  $E$  already introduced in quantum smoothing <sup>1</sup>

**Talk contribution:** how to compute the likelihood function  $\mathbb{P}(\mathbf{Y}/\rho_0)$  from the stochastic master equation governing filtering.

<sup>1</sup>Tsang PRL 2009, Gammelmark/Julsgaard/Mølmer PRL 2013, Guevara/Wiseman 2015...

Four features:

1. **Bayes law**:  $\mathbb{P}(\mu'/\mu) = \mathbb{P}(\mu/\mu')\mathbb{P}(\mu') / (\sum_{\nu'} \mathbb{P}(\mu/\nu')\mathbb{P}(\nu'))$ ,
2. **Schrödinger equations** defining unitary transformations.
3. **Randomness**, irreversibility and dissipation induced by the **measurement** of observables with **degenerate spectra**.
4. **Entanglement and tensor product for composite systems**.

⇒ **Discrete-time models**<sup>2</sup>

Take a set of operators  $\mathbf{M}_\mu$  satisfying  $\sum_\mu \mathbf{M}_\mu^\dagger \mathbf{M}_\mu = \mathbf{I}$  and a left stochastic matrices  $(\eta_{\mathbf{y}_t, \mu})$ . Consider the following **Markov process** of state  $\rho$  (density op.) and measured output  $\mathbf{y}$ :

$$\rho_{t+1} = \frac{\mathbf{K}_{\mathbf{y}_t}(\rho_t)}{\text{Tr}(\mathbf{K}_{\mathbf{y}_t}(\rho_t))}, \text{ with proba. } \mathbb{P}_{\mathbf{y}_t}(\rho_t) = \text{Tr}(\mathbf{K}_{\mathbf{y}_t}(\rho_t))$$

with  $\mathbf{K}_{\mathbf{y}}(\rho) = \sum_{\mu=1}^m \eta_{\mathbf{y}, \mu} \mathbf{M}_\mu \rho \mathbf{M}_\mu^\dagger$ . It is associated to the **Kraus map** (ensemble average, quantum channel)

$$\mathbb{E}(\rho_{t+1} | \rho_t) = \mathbf{K}(\rho_t) = \sum_{\mathbf{y}} \mathbf{K}_{\mathbf{y}}(\rho_t) = \sum_{\mu} \mathbf{M}_\mu \rho_t \mathbf{M}_\mu^\dagger.$$

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<sup>2</sup>see, e.g., the book of Haroche/Raimond and the publications around the LKB photon box.

**Discrete-time models:** Markov chains  $\rho_{t+1} = \frac{\mathbf{K}_{\mathbf{y}_t}(\rho_t)}{\text{Tr}(\mathbf{K}_{\mathbf{y}_t}(\rho_t))}$ , with

$\mathbf{K}_{\mathbf{y}_t}(\rho_t) = \sum_{\mu=1}^m \eta_{\mathbf{y}_t, \mu} \mathbf{M}_{\mu} \rho_t \mathbf{M}_{\mu}^{\dagger}$ , and proba.  $\mathbb{P}_{\mathbf{y}_t}(\rho_t) = \text{Tr}(\mathbf{K}_{\mathbf{y}_t}(\rho_t))$ .

Ensemble averages correspond to Kraus linear maps

$$\mathbb{E}(\rho_{t+1} | \rho_t) = \mathbf{K}(\rho_t) = \sum_{\mathbf{y}} \mathbf{K}_{\mathbf{y}}(\rho_t) = \sum_{\mu} \mathbf{M}_{\mu} \rho_t \mathbf{M}_{\mu}^{\dagger} \quad \text{with} \quad \sum_{\mu} \mathbf{M}_{\mu}^{\dagger} \mathbf{M}_{\mu} = \mathbf{I}$$

**Continuous-time models:** stochastic differential systems (see, e.g., Barchielli/Gregoratti, 2009)

$$d\rho_t = \left( -\frac{i}{\hbar} [\mathbf{H}, \rho_t] + \sum_{\nu} \mathbf{L}_{\nu} \rho_t \mathbf{L}_{\nu}^{\dagger} - \frac{1}{2} (\mathbf{L}_{\nu}^{\dagger} \mathbf{L}_{\nu} \rho_t + \rho_t \mathbf{L}_{\nu}^{\dagger} \mathbf{L}_{\nu}) \right) dt + \sum_{\nu} \sqrt{\eta_{\nu}} \left( \mathbf{L}_{\nu} \rho_t + \rho_t \mathbf{L}_{\nu}^{\dagger} - \text{Tr}((\mathbf{L}_{\nu} + \mathbf{L}_{\nu}^{\dagger}) \rho_t) \rho_t \right) dW_{\nu, t}$$

driven by Wiener processes  $dW_{\nu, t}$ , with measurements  $d\mathbf{y}_{\nu, t}$ ,

$d\mathbf{y}_{\nu, t} = \sqrt{\eta_{\nu}} \text{Tr}((\mathbf{L}_{\nu} + \mathbf{L}_{\nu}^{\dagger}) \rho_t) dt + dW_{\nu, t}$ , detection efficiencies

$\eta_{\nu} \in [0, 1]$  and Lindblad-Kossakowski master equations ( $\eta_{\nu} \equiv 0$ ):

$$\frac{d}{dt} \rho = -\frac{i}{\hbar} [\mathbf{H}, \rho] + \sum_{\nu} \mathbf{L}_{\nu} \rho \mathbf{L}_{\nu}^{\dagger} - \frac{1}{2} (\mathbf{L}_{\nu}^{\dagger} \mathbf{L}_{\nu} \rho + \rho \mathbf{L}_{\nu}^{\dagger} \mathbf{L}_{\nu})$$

The **Belavkin** quantum filter

$$d\rho_t = \left( -\frac{i}{\hbar} [\mathbf{H}, \rho_t] + \sum_{\nu} \mathbf{L}_{\nu} \rho_t \mathbf{L}_{\nu}^{\dagger} - \frac{1}{2} (\mathbf{L}_{\nu}^{\dagger} \mathbf{L}_{\nu} \rho_t + \rho_t \mathbf{L}_{\nu}^{\dagger} \mathbf{L}_{\nu}) \right) dt + \sum_{\nu} \sqrt{\eta_{\nu}} \left( \mathbf{L}_{\nu} \rho_t + \rho_t \mathbf{L}_{\nu}^{\dagger} - \text{Tr} \left( (\mathbf{L}_{\nu} + \mathbf{L}_{\nu}^{\dagger}) \rho_t \right) \rho_t \right) d\mathbf{W}_{\nu,t}$$

with  $d\mathbf{W}_{\nu,t} = d\mathbf{y}_{\nu,t} - \sqrt{\eta_{\nu}} \text{Tr} \left( (\mathbf{L}_{\nu} + \mathbf{L}_{\nu}^{\dagger}) \rho_t \right) dt$  given by the measurement signal  $d\mathbf{y}_{\nu,t}$ , is always a stable filtering process.<sup>3</sup> Using **Itô rules**, it can be written as a "discrete-time" Markov model<sup>4</sup>

$$\rho_{t+dt} = \mathbf{K}_{d\mathbf{y}_t}(\rho_t) / \text{Tr}(\mathbf{K}_{d\mathbf{y}_t}(\rho_t))$$

with "partial Kraus maps"

$$\mathbf{K}_{d\mathbf{y}_t}(\rho_t) = \mathbf{M}_{d\mathbf{y}_t} \rho_t \mathbf{M}_{d\mathbf{y}_t}^{\dagger} + \sum_{\nu} (1 - \eta_{\nu}) \mathbf{L}_{\nu} \rho_t \mathbf{L}_{\nu}^{\dagger} dt$$

$$\mathbf{M}_{d\mathbf{y}_t} = \mathbf{I} + \left( -\frac{i}{\hbar} \mathbf{H} - \frac{1}{2} \left( \sum_{\nu} \mathbf{L}_{\nu}^{\dagger} \mathbf{L}_{\nu} \right) \right) dt + \sum_{\nu} \sqrt{\eta_{\nu}} d\mathbf{y}_{\nu,t} \mathbf{L}_{\nu}$$

where the probability of outcome  $d\mathbf{y}_t = (d\mathbf{y}_{\nu,t})$  reads:

$$\mathbb{P} \left( d\mathbf{y}_t \in \prod_{\nu} [\xi_{\nu}, \xi_{\nu} + d\xi_{\nu}] / \rho_t \right) = \text{Tr}(\mathbf{K}_{\xi}(\rho_t)) \prod_{\nu} e^{-\xi_{\nu}^2/2dt} \frac{d\xi_{\nu}}{\sqrt{2\pi dt}}$$

<sup>3</sup>H. Amini et al., Russian J. of Math. Physics, 2014, 21, 297-315.

<sup>4</sup>PR, J. Ralph PRA2015; see also PR Int. Congress of Mathematicians at Seoul 2014, and PhD of Ph. Campagne-Ibracq at ENS-Paris, 2015.

- ▶ Denote by  $\mathbb{P}_n(\rho)$  the probability of getting measurement trajectory  $n$ ,  $(\mathbf{y}_t^{(n)})_{t=0,\dots,T}$ , knowing the initial state  $\rho_0^{(n)} = \rho$ .
- ▶ Since  $\rho_{t+1}^{(n)} = \frac{\mathbf{K}_{\mathbf{y}_t^{(n)}}(\rho_t^{(n)})}{\text{Tr}(\mathbf{K}_{\mathbf{y}_t^{(n)}}(\rho_t^{(n)}))}$  with  $\text{Tr}(\mathbf{K}_{\mathbf{y}_t^{(n)}}(\rho_t^{(n)}))$  the probability of having detected  $\mathbf{y}_t^{(n)}$  knowing  $\rho_t^{(n)}$ , a direct use of Bayes law yields  $\mathbb{P}_n(\rho) = \prod_{t=0}^T \text{Tr}(\mathbf{K}_{\mathbf{y}_t^{(n)}}(\rho_t^{(n)}))$ . Some elementary computations show that:

$$\mathbb{P}_n(\rho) = \text{Tr}(\mathbf{K}_{\mathbf{y}_T^{(n)}} \circ \dots \circ \mathbf{K}_{\mathbf{y}_0^{(n)}}(\rho)).$$

- ▶ The **adjoint map**  $\mathbf{K}_y^*$  of  $\mathbf{K}_y$  is defined by  $\text{Tr}(A\mathbf{K}_y(B)) \equiv \text{Tr}(\mathbf{K}_y^*(A)B)$  for all Hermitian operators  $A$  and  $B$ . Thus

$$\mathbb{P}_n(\rho) = \text{Tr}(\mathbf{K}_{\mathbf{y}_T^{(n)}} \circ \dots \circ \mathbf{K}_{\mathbf{y}_0^{(n)}}(\rho) \quad I) = \text{Tr}(\rho \mathbf{K}_{\mathbf{y}_0^{(n)}}^* \circ \dots \circ \mathbf{K}_{\mathbf{y}_T^{(n)}}^*(I)).$$



- ▶ The normalized **adjoint quantum filter**,  $E_t^{(n)} = \frac{\mathbf{K}_{y_t^{(n)}}^* (E_{t+1}^{(n)})}{\text{Tr} \left( \mathbf{K}_{y_t^{(n)}}^* (E_{t+1}^{(n)}) \right)}$

with  $E_{T+1}^{(n)} = I / \text{Tr}(I)$ , defines a family of Hermitian and non-negative operators ( $E_t^{(n)}$ ) on unit trace depending only on the measurement data  $\mathbf{Y}$ .

- ▶ We have  $\mathbf{K}_{y_0^{(n)}}^* \circ \dots \circ \mathbf{K}_{y_T^{(n)}}^* (I) = g_n(\mathbf{Y}) E_0^{(n)}$  with  $\frac{1}{g_n(\mathbf{Y})} = \text{Tr} \left( \mathbf{K}_{y_0^{(n)}}^* \circ \dots \circ \mathbf{K}_{y_T^{(n)}}^* (I) \right)$  independent of  $\rho$ .
- ▶ Thus  $\mathbb{P}_n(\rho) = g_n(\mathbf{Y}) \text{Tr} \left( \rho E_0^{(n)} \right)$  and

$$\mathbb{P}(\mathbf{Y}/\rho) = g(\mathbf{Y}) \prod_{n=1}^N \text{Tr} \left( \rho E_0^{(n)} \right)$$

where  $g(\mathbf{Y}) = \prod_{n=1}^N g_n(\mathbf{Y})$ .

- ▶ MaxLike tomography based on POVM  $\pi_j$ :  $\rho_{ML}$  maximizes

$$\mathbb{P}(\mathbf{Y} \mid \rho) = \prod_j (\text{Tr}(\rho\pi_j))^{N_j} = \prod_n \text{Tr}(\rho\pi_{j_n})$$

with  $\mathbf{Y} \equiv (N_j)$  derived from  $j_n$ , the measurement outcome number  $n = 1, \dots, N$ .

- ▶ MaxLike tomography based on the adjoint states:  $\rho_{ML}$  maximizes

$$\mathbb{P}(\mathbf{Y} \mid \rho) = g(\mathbf{Y}) \prod_n \text{Tr}(\rho E^{(n)})$$

where  $E^{(n)} = E_0^{(n)}$  is the adjoint state at  $t = 0$  associated to measurement trajectory  $(\mathbf{y}_t^{(n)})$  number  $n$ .

**Convex optimization problem:** the set  $\mathcal{D}$  of density operators is convex; the log-likelihood function  $f : \mathcal{D} \ni \rho \mapsto \log(\mathbb{P}(\mathbf{Y} \mid \rho))$  is concave (see Robert Kosut talk ...)

We have

$$f(\rho) \triangleq \log(\mathbb{P}(\mathbf{Y} | \rho)) = \log(g(\mathbf{Y})) + \sum_{n=1}^N \log\left(\text{Tr}\left(\rho E^{(n)}\right)\right).$$

The gradient of  $f$ ,

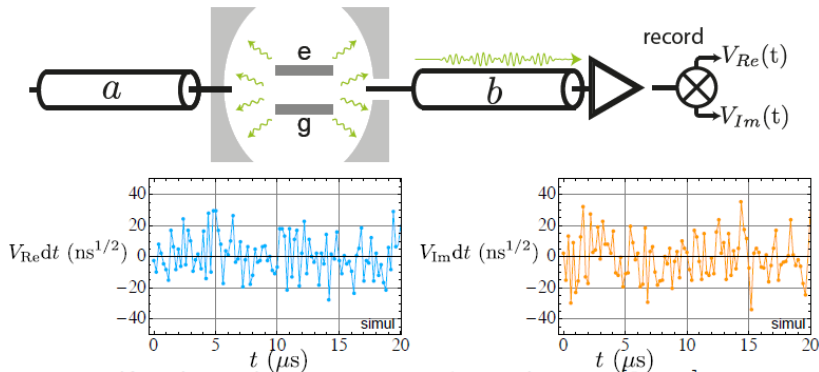
$$\nabla f_{\rho} = \sum_{n=1}^N \frac{E^{(n)}}{\text{Tr}(E^{(n)}\rho)}.$$

and its Hessian  $\nabla^2 f$  (self-adjoint super-operator)

$$\xi \mapsto \nabla^2 f_{\rho}(\xi) = - \sum_{n=1}^N \frac{\text{Tr}(E^{(n)}\xi)}{\text{Tr}^2(E^{(n)}\rho)} E^{(n)}.$$

result from the following second order expansion:

$$\begin{aligned} f(\rho + \delta\rho) - f(\rho) &= \sum_{n=1}^N \left( \frac{\text{Tr}(E^{(n)}\delta\rho)}{\text{Tr}(E^{(n)}\rho)} - \frac{1}{2} \frac{\text{Tr}^2(E^{(n)}\delta\rho)}{\text{Tr}^2(E^{(n)}\rho)} \right) + o(\text{Tr}(\delta\rho^2)) \end{aligned}$$

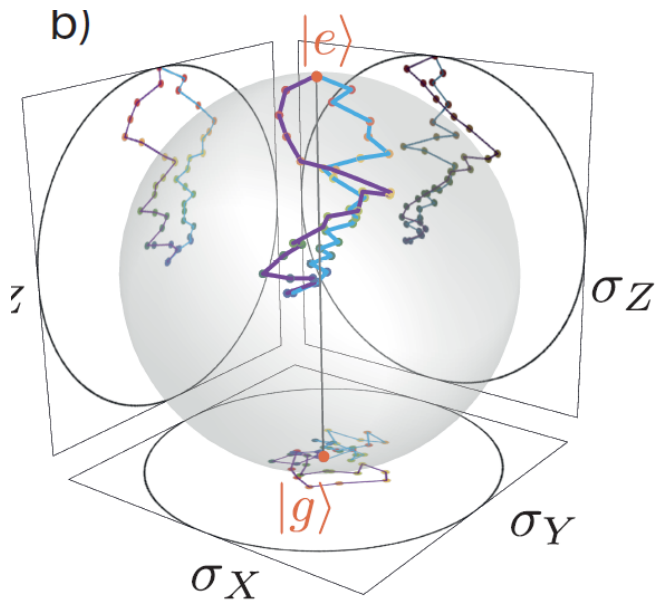


No drive  $\mathbf{H} = 0$ ,  $\nu \in \{1, 2, 3\}$

Two fluorescence measurements  $\mathbf{L}_1 = \sqrt{\frac{1}{2T_1}} \boldsymbol{\sigma}_x$  and  $\mathbf{L}_2 = i\mathbf{L}_1$  with  $T_1 = 4 \mu\text{s}$  and efficiencies  $\eta_1 = \eta_2 \approx 1/4$ .

Dephasing channel  $\mathbf{L}_3 = \sqrt{\frac{1}{2T_\phi}} \boldsymbol{\sigma}_z$  with  $T_\phi = 35 \mu\text{s}$  ( $\eta_3 = 0$ ).

<sup>5</sup>Ph. Campagne-Ibracq et al., Phys. Rev. Lett., 2014, 112, 180402.



- ▶  $N = 3000$  trajectories of length  $T = \frac{5}{2} T_1$ , with  $dt = \frac{1}{20} T_1$
- ▶ Two measurements of efficiency  $\eta = \frac{1}{4}$ :

$$dy_1 = \sqrt{\frac{\eta}{2T_1}} \text{Tr}(\rho \sigma_x) + dW_1, \quad dy_2 = \sqrt{\frac{\eta}{2T_1}} \text{Tr}(\rho \sigma_y) + dW_2$$

For each trajectory, the data corresponds to  $2 \times 50$  real values ( $dt = 200$  ns).

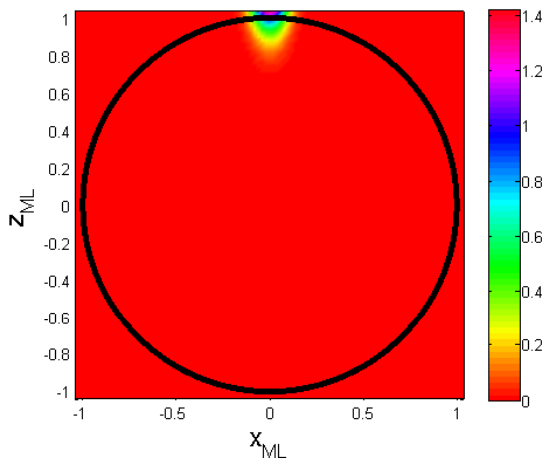
- ▶ The resulting  $\rho_{ML}$

$$x_{ML} = 0.0134, \quad y_{ML} = 0.0213, \quad z_{ML} = 0.9997$$

is pure since it satisfies  $x_{ML}^2 + y_{ML}^2 + z_{ML}^2 = 1$ .

- ▶ Gradient and Hessian of the log-likelihood function  $f$

$$\nabla f_{\rho_{ML}} = \begin{pmatrix} 0.12 \\ 0.20 \\ 9.22 \end{pmatrix}, \quad \nabla^2 f_{\rho_{ML}} = \begin{pmatrix} -241.1 & 3.6 & 0.4 \\ 3.6 & -235.7 & 1.4 \\ 0.4 & 1.4 & -23.5 \end{pmatrix}$$



$N = 3000$  fluorescence trajectories of length  $2T_1$ .  
Cross section passing through the center of Bloch sphere  
 $z_{ML}$ -axis aligned with  $\rho_{ML}$ , close to  $z$ -axis,  $x_{ML}$ -axis close to  $x$ -axis.

- ▶  $N = 3000$  trajectories of length  $T = 2T_1$ , with  $dt = \frac{1}{20}T_1$ .
- ▶ Two measurements of efficiency  $\eta = \frac{1}{4}$ :

$$dy_1 = \sqrt{\frac{\eta}{2T_1}} \text{Tr}(\rho\sigma_x) + dW_1, \quad dy_2 = \sqrt{\frac{\eta}{2T_1}} \text{Tr}(\rho\sigma_y) + dW_2$$

For each trajectory, the data corresponds to  $2 \times 40$  real values ( $dt = 200$  ns).

- ▶ The resulting  $\rho_{ML}$

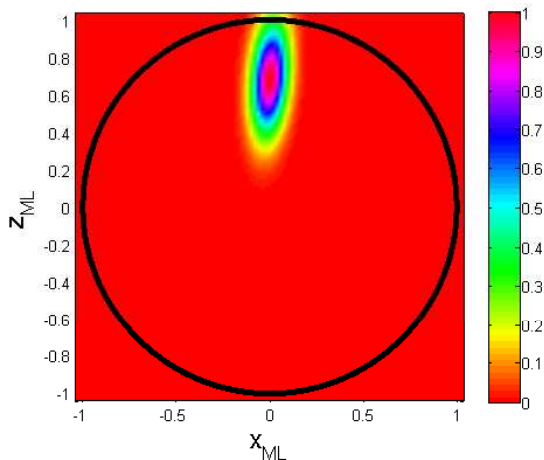
$$x_{ML} = -0.0465, \quad y_{ML} = 0.0625, \quad z_{ML} = 0.6787$$

is mixed since it satisfies  $x_{ML}^2 + y_{ML}^2 + z_{ML}^2 < 1$ .

- ▶ Gradient and Hessian of the log-likelihood function  $f$ :

$$\nabla f_{\rho_{ML}} = 0, \quad \nabla^2 f_{\rho_{ML}} = \begin{pmatrix} -231.6 & -2.6 & 1.7 \\ -2.6 & -227.5 & -0.4 \\ 1.7 & -0.4 & -21.6 \end{pmatrix}$$





$N = 3000$  fluorescence trajectories of length  $\frac{3}{2} T_1$ .  
Cross section passing through the center of Bloch sphere  
 $z_{ML}$ -axis aligned with  $\rho_{ML}$ , close to  $z$ -axis,  $x_{ML}$ -axis close to  $x$ -axis.

- ▶ Another possible estimation is given by  $\rho_{BM} \propto \int \rho \mathbb{P}(\mathbf{Y} | \rho) \mathbb{P}_0(\rho) d\rho$  with some prior distribution  $\mathbb{P}_0(\rho) d\rho$ .
- ▶ With Bloch variables  $(x, y, z)$  and  $\mathbb{P}_0(\rho) d\rho \propto dx dy dz$  we have,

$$x_{BM} = \frac{\iiint_{x^2+y^2+z^2 \leq 1} x e^{f(x,y,z)} dx dy dz}{\iiint_{x^2+y^2+z^2 \leq 1} e^{f(x,y,z)} dx dy dz}, \quad y_{BM} = \dots$$

- ▶ With the normalization  $f = \bar{N} \bar{f}$  with  $\bar{N} > 0$  large, we have approximation of  $x_{BM}$  via the asymptotics

$$\iiint_{x^2+y^2+z^2 \leq 1} g(x, y, z) e^{\bar{N} \bar{f}(x,y,z)} dx dy dz = \frac{e^{\bar{N} \bar{f}(x_{ML}, y_{ML}, z_{ML})}}{\bar{N}^2} \left( c_0 + \frac{c_1}{\bar{N}} + \frac{c_2}{\bar{N}^2} + \dots \right)$$

where  $c_0, c_1, c_2 \dots$  depend on the derivatives of  $\bar{f}$  and  $g$  at  $(x_{ML}, y_{ML}, z_{ML})$ <sup>6</sup>

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<sup>6</sup>For an elementary theory see Bleistein, N. Handelsman, R. : Asymptotic Expansions of Integrals. Dover, 1986.

For the general recent theory called Singular Learning see Watanabe S., Algebraic Geometry and Statistical Learning Theory, Cambridge University Press, 2009.

See also Shaowei Lin, Algebraic Methods for Evaluating Integrals Bayesian Statistics, PhD thesis, University of California, Berkeley, 2011.

1. Another validation on the **experimental data of the LKB photon box** underlying Rybarczyk et al: Past quantum state analysis of the photon number evolution in a cavity, to appear in PRA.  
Compensation of photon life-time  $1/\kappa$  comparable with the time during the QND measurement of photons.
2. In the near future: application to **Wigner tomography of a cavity field** based on the measurement protocol used, e.g., in Leghtas et al.: Confining the state of light to a quantum manifold by engineered two-photon loss; Science, 2015, 347, 853-857.  
Compensation for initial thermal state of the probe qubit, qubit measurement errors, cavity field damping and several nonlinear Kerr effects.
3. Extension to **parameter estimation** (quantum process tomography) where the adjoint state simplifies the gradient computation of the log-likelihood function.
4. Correction to low-rank  $\rho_{ML}$  via  $\rho_{BM} \propto \int \rho \mathbb{P}(\mathbf{Y} | \rho) \mathbb{P}_0(\rho) d\rho$  and its approximate computation via asymptotics techniques developed for **multidimensional integrals of Laplace type**.